

Accelerating 3D Convolution using Streaming Architectures

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Summary

We investigate dataflow engine (DFE) architectures for accelerating applica-tions whose dominant cost is 3D convolution, such as

modeling and Reverse Time Migration (RTM).

We explore design options such as: (1) using different stencils; (2) fitting multiple stencil operators into the DFE; (3) processing multiple time steps in one pass; and (4) customizing the computation precisions. In this paper we examine MAX2 DFEs and MAX3 DFEs.

Finite-difference based convolution operators perform multiplications and additions on a number of adjacent points. From a memory perspective, however, these points are often stored far apart inducing a large number of cache misses in software implementations.

In a DFE implementation, a memory buffer stores the points located in memory between the first and last points of the stencil operator applied to a given data item. For a 7-point 3D convolution on a 512 x 512 x 512 array, the design requires a buffer for $512 \times 512 \times 6$ data items.

We experiment with two different 3D stencils: a 7-point star stencil (*Figure 1a*) and a 3-by-3-by-3 cube stencil (*Figure 1b*) which perform respectively an 8th and 6th order finite d ifference. While



Figure 1: 2 Alternative stencil choices.



Figure 2: Speedups for processing different numbers of timesteps in each pass with each stencil type.

the cube consumes 20% more arithmetic units in the DFE than the star, the internal-DFE-memory requirement of the cube is one third of the star. By exploiting the symmetry of the coefficients, the number of arithmetic operations reduces significantly for the cube.

To make a full utilization of all units on a DFE, we have two options: (1) using multiple stencil operators to work on multiple data items in parallel; (2) processing multiple timesteps in one pass.

Increasing the number of stencil operators may not improve the performance when the input streams approach the memory bandwidth limit: both the cube and the star arrive at the saturation point of around 25x speedup with four stencil operators.

The other strategy is to process multiple timesteps in one pass, with the output of each unit as the input of the next unit. This solution will not be limited by memory bandwidth and will allow improving the order-of-time accuracy with relatively small costs. *Figure 2* shows projected performance for the star and cube stencils over multiple timesteps. The cube stencil scales much better than the star stencil as the buffering requirements for the cube are a third those of the star.

We have implemented the 2nd order cube with 6 time steps onto the Maxeler MAX2 DFE an achieved a speedup of 29x. By using the MAX2 card, we achieved up to 55x speedup. On the new MAX3 DFE, we can fit up to 13 time steps on the card and achieve up to 110x speedup compared to a single-core CPU version.